

Geo-Vista

Integrated Logging While Drilling System (InteLWD)

Bi-directional Communication Power Module (BCP-O) Drilling Dynamics Monitor (DDM)

Integrated Logging While Drilling Tool (LWD-O)

Rotary Steerable Unit (RSU)

Near-Bit Azimuth Gamma Ray (NB-AGR) Caliper Corrected Neutron Porosity (CCN)

Rotary Azimuthal Density (RAD) Azimuthal Resistivity While Drilling (ARD)

Nuclear Magnetic Resonance Imaging While Drilling (MRI)

Acoustic While Drilling (AWD)

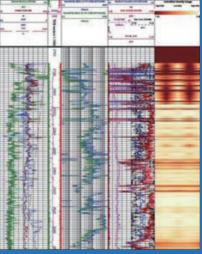
Ultrasonic Imaging While Drilling (UID)

Pressure & Caliper Measurement While Drilling (PCD)

Ultrasonic Caliper Measurement While Drilling (CWD)

Generator Caliper Corrected Neutron Porosity (GCN) Formation Tester While Drilling (FTD)



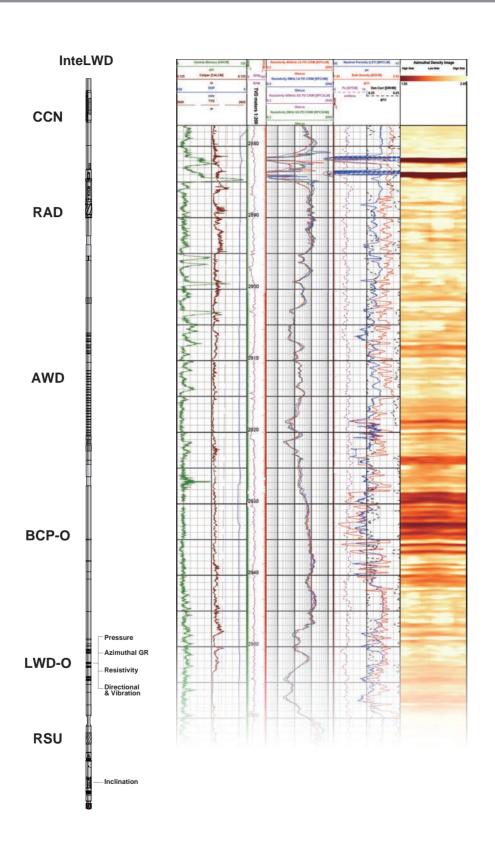




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Rotary steering system BHA configuration with CCN-RAD

HWDP

Centralizer Sub

Crossover sub Box NC38/NC50 To GT6

Caliper Corrected Neutron Porosity (CCN)

Rotary Azimuthal Density (RAD)

Bi-directional Communication Power Module (BCP-O)

Drilling Dynamics Monitor (DDM)

Upper Centralizer Sub (UCS)

Battery Management Unit (BAT)

Integrated Logging While Drilling Tool (LWD-O)

Lower Centralizer Sub (LCS)

Rotary Steerable Unit (RSU)

Rotary steering system BHA configuration with GCN

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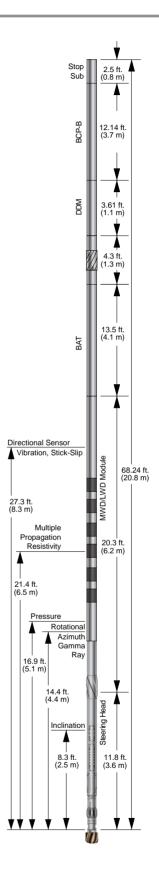




Introduction

InteLWD is the new generation logging while drilling system, this system integrates the measurement of orientation, gamma, resistivity, borehole & annular pressure and drilling tool vibration, this system realize combined with CCN (Caliper Corrected Neutron Porosity), RAD (Rotary Azimuthal Density), MRI (Nuclear Magnetic Resonance Imaging While Drilling), AWD (Acoustic While Drilling), PCD (Pressure & Caliper Measurement While Drilling) and FTD (Formation Tester While Drilling). Improve the reliability of tools, reduced the connection point, and make the sensors distance from BHA to Bit optimized. This system also can realize the bi-directional communication with the surface system at the same time, can be combined with the rotation direction (RSU) realize geosteering.

Hole size		5-7/8 in. to 6-3/4 in.	
OD)	4-3/4 in.	
	Up	NC38 box	
Connection	Down	3-1/2 in. Reg box	
Build F	Rate	0-10°/100 ft. (0-10°/30 m)	
Max.	Rotation	10°/100 ft. (10°/30 m)	
Dogleg	NO rotation	30°/100 ft. (30°/30 m)	
Flow Ra	ange	125-350 GPM	
Pow	er	Drilling fluid driven Turbine	
Max. R	RPM	400 rpm	
Max. Temp	perature	302°F (150°C)	
Max. Pre	essure	20000 psi (138 MPa)	
Sand Content		≤1%	
Max. LCM		40 ppb=114 kg/m ³	
Vibrat	ion	5 g RMS	

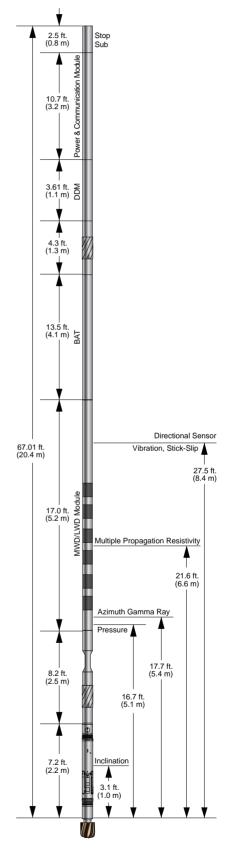




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Hole size OD		8-1/2 in. to 10-5/8 in.	12 in. to 17-1/2 in.	
		6-3/4 in.	9-1/2 in.	
	Up	NC50 box	7-5/8 in. Reg box	
Connection	Down	4.4/0 in Dankan	7-5/8 in. Reg box	
	Down	4-1/2 in. Reg box	6-5/8 in. Reg. box	
Build Rat	е	0-6.5°/100 ft.	0-6.5°/100 ft.	
Max.	Rotation	13°/100 ft. (13°/30 m)	6.5°/100 ft. (6.5°/30 m)	
Dogleg	NO rotation	20°/100 ft. (20°/30 m)	13°/100 ft. (13°/30 m)	
Flow Rang	ge	200-900 GPM	300-1600 GPM	
Power		Drilling fluid driven Turbine		
Max. RPI	М	400 rpm		
Max. Temper	ature	302°F (150°C)		
Max. Press	Max. Pressure		138 MPa)	
Sand Content Max. LCM		≤1% 40 ppb=114 kg/m³		
				Vibration





Specifications

Pressure			
Range	0 - 25000 psi		
Resolution	5 psi		
Accuracy	±0.25% of full scale		
	GR		
Tool Type	Scintillation Crystal		
Range	0-500 API		
Accuracy	± 2.5 API/100 API		
Vertical Resolution	6 in. (153 mm)		
Vibration			
D	Axial vibration z-Accelerometer		
Probe Type	Lateral vibration x-y Accelerometer		
Accleration Range	0 to 15 g		
Frequency Range	0 to 82 Hz		
Rota	ating & stick slip		
Probe Type	Two Axis Magnetometer		
Range	0 to ±1000 rpm		
Accuracy	±1%		

Electronic Magnetic Resistivity			
2 MHz Resistivity			
	Range	0.1 - 3,000 ohm-m	
Phase Difference	A	±1% (0.1-50 ohm-m)	
	Accuracy	±0.5 mmho/m (>50 ohm-m)	
	Range	0.1 - 500 ohm-m	
Attenuation	Acquirect	±2% (0.1-25 ohm-m)	
	Accuracy	±1 mmho/m (>25 ohm-m)	
V 6 15 16	8 in. (20 cm)		
Vertical Resolution	for 90% response in conductive beds		
400 kHz Resistivity			
	Range	0.1 - 1,000 ohm-m	
Phase Difference	Accuracy	±1% (0.1-25 ohm-m)	
		±1 mmho/m (>25 ohm-m)	
	Range	0.1 - 200 ohm-m	
Attenuation	A	±5% (0.1-10 ohm-m)	
	Accuracy	±5.0 mmho/m (>10 ohm-m)	
V # 15 1 #	12 in. (30 cm)		
Vertical Resolution	for 90% response in conductive beds		

Azimuthal Module

inatha modulo			
О Т	Tri-axial Accelerometer		
Sensor Type		Tri-axial Flux Gate	
MTF/GTF	Operator selectable (default: 3°)		
Measurement	Range	Resolution	Accuracy
Inclination	0°-180°	0.09°	± 0.15°
Azimuth	0°-360°	0.35°	± 1°
Toolface			
Magnetic TF	0°-360°	1.4°	± 1.5°
Gravity TF	0°-360°	1.4°	± 1.5°
Total Magnetic Field	0-100000 nT	35 nT	± 300 nT
Dip Angle	-90°~90°	0.04°	± 0.3°





- Transmission of downhole data to surface.
- High density downhole sensor data storage.
- Transmission of surface commands to downhole.

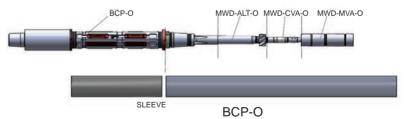
Introduction

Bi-directional Communication Power Module (BCP-O) and downlink devices (BPC, NPG). The BCP-O (Bi-Directional Communication & Power Module-O) is capable of generating 300 Watt power output, providing 33 Vdc to the InteLWD system, providing circuit breaker protection for upper and lower mounted instruments, detecting downlink data by monitoring turbine speed, transmitting data to the surface via a pulser. It can be installed in any position of the instrument string, which provides a lot of conveniences for the logging.

The BPC (Bypass Controller) sends commands from the surface to downhole instrument by controlling the NPG (Negative Pulse Generator) which controls the mud flow.

Specifications

Tool O.D.	4.75 in. 6.75 in.		9.5 in.	
Pulser Type	Rota	Rotary Pulser/Solenoid F		
May Draggura	20,000 psi	20,000 psi (137.9 MPa)/		
Max. Pressure	25000 psi (172	2 MPa) (option)	20,000 psi (137.9 MPa)	
Max. Temperature	300°F (150°C)/35	0°F (175°C) (option)	300°F (150°C)	
Make-up Length	12.10 ft. (3.7 m)	, , , , , ,		
Weight	903 lbs. (410 kg)			
Flow Range	125-350 gpm	200-900 gpm	300-1600 gpm	
		0.2 bit/s~3 bit/s		
Transmission Rates	Pulse Width Selectable: 3.0/2.0/1.5/			
	1.0/0	1.0/0.8/0.5/0.36/0.32/0.24 sec		
Max. Turbine RPM	7000			
Output				
Max. Power Output				





Safe Direction Drilling Panel (SDD)

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Negative Pulse Generator (NPG)



■ Judge Bit working Condition

Introduction

Drilling Dynamics Monitor (DDM) can measure Weight On Bit (WOB), BHA Torque, Hole Pressure and Annular Pressure, and transmit to surface via positive pulse. According the sensor data, drilling operator can modify the drilling parameter, mud equivalent circulation density, and drill safely and quickly.

Outside Diameter 4.75 in. (120 mm) / 6.75 in.) / 6.75 in. (172 mm)	
Max Tempreature	300°F (150°C) 20,000 psi (137.9 MPa)		
Max Pressure			
Connector	Up	GVT2 Pin	
Connector	Down	GVT2 Box	
Dogleg	16°/100 ft. (16°/30 m) @ Slidding		
Dogleg	9°/100 ft. (9°/30 m) @ Rotation		
T 11 0		3.61 ft. (1.1 m)	
WOB Measure Range	±300 kN		
Accuracy	±5%		
Torque Measure Range	±30 kNm ±5%		
Accuracy			







- Flow-off directional surveys
- Directional surveys connected downhole motor on BHA top

Introduction

The Battery Management Unit provides directional sensor power during flow-off, acquire survey data, and store the data. Transmit the survey data to surface after flow-on.

Maximum Temperature	350°F (175°C)
Maximum Pressure	20,000 psi (137.9 MPa)
	3.375 in. (85.7 mm)
0.44.5	4.75 in. (120.7 mm)
Outside Diameter	6.75 in. (171.5 mm)
	8.25 in. (209.5 mm)
Length	13.5 ft. (4.11 m)
0 "	GVT2 Box Up
Connections	GVT2 PIN Down





- Maximized drilling efficiency and wellbore placement with automated rotary drilling.
- Reduced risk of differential sticking via continuous rotation.
- Extended horizontal and lateral capabilities for maximum payzone contact—increasing production rates and extending the life of the well.
- Improved hole quality and hole cleaning to reduce completion risks.

Introduction

LWD-O combines real-time azimuth, gamma ray, resistivity, annulus pressure and vibration measurement together. This reduces the number of connection joints, improve reliability, and optimize the distance from BHA sensors to drilling bit. InteLWD consists BCP-O, directional sensor, resistivity, pressure sensor, gamma ray, master controller memory.

Specifications

Max. Temperature	300°F (150°C)	
Max. Pressure	20,000 psi (137.9 MPa)	
Max. Rotation Rate	400 rpm	
Max. Lost Circulation Material	40 ppb=114 kg/m ³	

Tool O.D. Make-up Length		4.75 in.	6.75 in.	9.5 in	
		20.34 ft. (6.2 m)	17.06 ft. (5.2 m)	18.1 ft. (5.5 m)	
Hole Diameter		5-3/4 in. to 6-3/4 in.	8-3/8 in. to 10-5/8 in.	12 in. to 17-1/2 in.	
		(146-172 mm)	(212-270 mm)	(305-445 mm)	
Dogleg	With Rotation	10°/100 ft. (10°/30 m)	13°/100 ft. (13°/30 m)	6.5°/100 ft. (6.5°/30 m)	
Severity	Without Rotation	30°/100 ft. (30°/30 m)	20°/100 ft. (20°/30 m)	13°/100 ft. (13°/30 m)	
Max	. Temperature	300°F (150°C) Upon Request 350°F (175°C)			
Max. Pressure Max. Rotation Rate		20,000 psi (137.9 MPa)			
		400 rpm			
Max. Lost Circulation Material					
		40 ppb=114 kg/m ³			

Directional Sensor Vibration, Stick-Slip

Azimuth Gamma Ray

Annular Pressure

Resistivity

ans dots





- Precise reservoir navigation
- Exact wellbore placement
- Early detection of bed boundaries
- Geo-confirmation of sedimentary structures
- Offers a smooth wellpath and excellent hole quality for faster completions and enhanced production.
- Identifies hole cleaning problems and fluid influx into the wellbore.
- Optimizes drilling performance and reliability
- Increased Rate Of Penetration (ROP)

Introduction

RSU is based on closed-loop systems with new designed MWD technique. It allows steering to target by advanced directional control methods in most challenging wellbore trajectories. Adds any LWD tools or borehole optimization systems into integrated BHA follow application needs.

	Too	l O.D.	4.75 in.	6.75 in.	9.5 in.	
	Max. Pressure Max. Temperature Make-up Length		20,000 psi (137.9 MPa)			
			300°F (150°C)			
			14.55 ft. (4.4 m) 7.22 ft. (2.2 m)		8.2 ft. (2.5 m)	
	W	eight	881 lbs. (400 kg)	905 lbs. (410 kg)	3,638 lbs. (1650 kg)	
	Hole Diameter		6 in. to 6-3/4 in.	8-3/8 in. to 10-5/8 in.	12 in. to 17-1/2 in.	
			(152-172 mm)	(212-270 mm)	(305 mm-445 mm)	
	Build Rate With		2 422/422 (0-6.5°/100 ft. (30 m)	0.0 = 0/4.00 % /00)	
			0-10°/100 ft. (30 m)	0-15°/100 ft. (30 m)	0-6.5°/100 ft. (30 m)	
			10°/100 ft.	13°/100 ft.	6.5°/100 ft.	
	Dogleg	Rotation	(10°/30 m)	(13°/30 m)	(6.5°/30 m)	
	Severity	Without	30°/100 ft.	20°/100 ft.	13°/100 ft.	
		Rotation	(30°/30 m)	(20°/30 m)	(13°/30 m)	



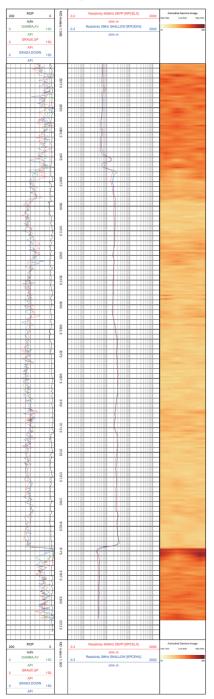




■ Horizontal well geosteering and formation evaluation

Achieve precise window-in target Accurately identify the change direction of the geological structure of the drilled reservoir and increase the rate of drilled encounters

Reduce cycle and waiting time Improve drilling efficiency



Introduction

Near-bit azimuth gamma can accurately measure near-bit inclination and gamma, and provide early formation recognition during drilling.

Tool Size	4.75 in.	6.75 in.
Max Pressure	20000 psi (137.9 Mpa)	
Max Temperature	300°F (150°C)	
Gamma Speci	fication	
Crystal Type	Scin	tillation
Measurement	AP	'I GR
Measuring Range	0 - 2	50 API
Measuring Accuracy	±3% API	of full scale
Vertical Resolution	6 in. (153 mm)
Inclination Spec	cification	
	X-Y axis a	ccelerometer
Sensor Type	Z axis ac	celerometer
Measuring Range	0 -	180°
Measuring Accuracy	±1°@	NC>30°
Electromagnetic	Wave Type	
Tool Length	914	1 mm
Tool OD	5.4 in. (138 mm)	7.25 in. (184 mm)
Modulation Type	ASK 20 Baud	
Baud Rate		
Supply Voltage	7.	3 V
Current and Power	470 mA @ 7	7.3 V (3.43 W)
Connection	4-1/2	2 REG
Transmission Distance	2	0 m
Battery working time	150	hours
Inclination and gamma measurement points	450 mm (Bel	nind the drill bit)
Electric Cu	rrent	
Tool Length	91	4mm
Tool OD	5.4 in. (138 mm)	7.25 in. (184 mm)
Modulation Type	GI	MSK
Baud Rate	20	Baud
Supply Voltage	+12 V to +24 V	
Current and Power	120 mA @ 22 V (2.64 W)	
Connection	4-1/2 REG	
Transmission Distance	stance 20 m	
Battery working time 240 hours		
Inclination and gamma measurement points	450 mm (Behind the drill bit)	
·		





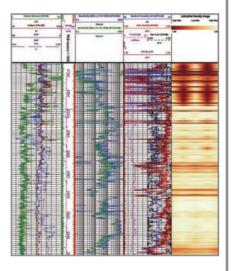


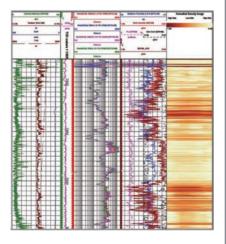
Caliper Corrected Neutron Porosity-**Rotary Azimuthal Density-4.75** (CCN-RAD-4.75)



Applications

- Accurate, real-time quantification of porosity and gas identification for saturation calculations.
- Reservoir Navigation using high-resolution imaging and gas-oil/water identification in
- Wellbore stability analysis using azimuthal caliper and density imaging in real-time.
- Structural formation dip analysis and updating reservoir models from density imaging.





Introduction

CCN-RAD offers measurement of formation density, neutron porosity, borehole caliper, and formation imaging. That provides geosteering for maximum reservoir exposure. Neutron porosity and bulk density are critical for the quantification of hydrocarbons in the reservoir.

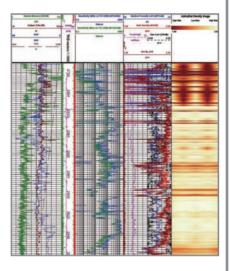
Diameter	4.75 in. With 5.59 in. upset	
Max. Pressure	20000 psi (137.9 MPa)	
Max. Temperature	300°F (150°C)	
Weight		1100 lbs. (498 kg) (CCN-RAD 4)
Max. Dogleg Severity		15°/100 ft. (15°/30 m) Rotating 30°/100 ft. (30°/30 m) Sliding
CCN		
Service		Formation Porosity
Tool Type		Caliper Corrected Neutron
Detectors	Lith	ium-6 lodide Crystal with Photomultiplier tube for both Near and Far detectors
Porosity Accuracy	0.5 p	ou below 10 pu, 5% of reading for 10-50 pu
Vertical Resolution		24 in. (61 cm)
Statistical Repeatability		± 0.6 pu@20 pu @ 200 ft./hr.
Max. Logging Speed		180 ft./hr (@2 points/ft.)
Depth Of Investigation	10) in. estimated for 8.5 in. 10 pu borehole
Radioactive Source	А	m 241-Be Strength: 5 Curies (185 GBq)
Measure Point	4	.6 ft. (1.4 m) (From downhole tool end)
Voltage		30 Vdc
Current Draw		160-170 mA
RAD		
Service	Forma	ation Bulk Density Service with Hole Caliper
Tool Type		Rotational Azimuthal Density
Detectors	Nal Scintillation Crystal with photomultiplier tube for both Long and Short Spaced detectors	
Density Specifications		
Range		1.6-3.1 g/cc
Accuracy	± 0.025 g/cc@200 ft./hr (60 m/hr) and 2.5 g/cc	
Statistical Repeatability	18 in. (45 cm) (full resolution)	
Downhole End Measure Po	, , , , , , , , , , , , , , , , , , , ,	
Photoelectric Factor Specif	ications	
Range		1-10 Barnes/electron (B/e)
Accuracy		± 0.25 B/e from 2-5 B/e
Statistical Repeatability		± 0.25 B/e@200 ft./hr (60 m/hr)
Vertical Resolution		6 in. (150 mm) (full resolution)
Downhole End to Pe Meas	ure Point	5.1 ft. (1.5 m)
Acoustic Standoff Caliper S	Specification	ons
Range	0-2 in. (Out of housing)	
Accuracy	±0.075 in. (0 to 0.5 in.) ±0.125 in. (0.5 to 1.0 in.) ±0.25 in. (1.0 to 2.0 in.) Out of housing	
Max. Logging Speed	180 ft./hr (@2 points/ft.)	
	Cs137 Strength: 2 Curies (74 GBq)	
Radioactive Source		CS137 Siterigiti. 2 Guiles (74 Gbq)
Radioactive Source Voltage		30 V



Caliper Corrected Neutron Porosity (CCN) Geo-Vista

Applications

- Accurate, real-time quantification of porosity and gas identification for saturation calculations.
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- Structural formation dip analysis and updating reservoir models from density imaging.



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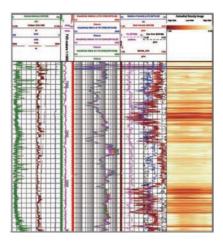
Diameter	6.75 in. with	8.25 in. With
Diameter	7.50 in. upset	10.125 in. upset
Max. Pressure	20000 psi (137.9 MPa)	
Max. Temperature	300°F	(150°C)
Weight	893 lbs. (405 kg)	1325 lbs. (600 kg)
Service	Formatio	n Porosity
Tool Type	Caliper Corre	ected Neutron
	9°/100 ft. (9°/30 m)	6.5°/100 ft. (6.5°/30 m)
Dogleg Severity	Rotating	Rotating
Dogleg Severity	16°/100 ft. (16°/30 m)	12°/100 ft. (12°/30 m)
	Sliding	Sliding
Detectors	Lithium-6 lodide Crystal with Photomultiplier	
Detectors	tube for both Near and Far detectors	
Porosity Accuracy	0.5 pu below 10 pu, 5% of reading for 10-50 pu	
Vertical Resolution	24 in. (61 cm)	
Statistical Repeatability	± 0.6 pu@20 pu @ 200 ft./hr.	
Max. Logging Speed	180 ft./hr (@2 points/ft.)	
Depth Of Investigation	10 in. estimated for 8.5 in. 10 pu borehole	
Radioactive Source	Am 241-Be Strength: 5 Curies (185 GBq)	
Measure Point	4.6 ft. (1.4 m) (From downhole tool end)	
Voltage	30 Vdc	
Current Draw	160-170 mA	







- Accurate, real-time quantification of porosity and gas identification for saturation calculations.
- Reservoir Navigation using high-resolution imaging and gas-oil/water identification in real-time.
- Wellbore stability analysis using azimuthal caliper and density imaging in real-time.
- Structural formation dip analysis and updating reservoir models from density imaging.
- 8 or 16 sector azimuthal density, Pe and borehole caliper measurements.



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eter	6.75 in.	8.25 in.
essure	20000 psi (137.9 MPa)	
perature	300°F (150°C)	
ght	1092 lbs. (495 kg) 1945 lbs. (881 kg)	
ice	Formation Bulk Density Se	ervice with Hole Caliper
Гуре	Rotational Azim	uthal Density
Rotating	9°/100 ft. (9°/30 m)	6.5°/100 ft. (6.5°/30 m)
Sliding	16°/100 ft. (16°/30 m)	12°/100 ft. (12°/30 m)
	Nal Scintillation Crystal with photomultiplier tube for	
ctors	both Long and Short	Spaced detectors
	Density Specifications	
ge	1.6-3.1	g/cc
racy	± 0.015	g/cc
epeatability	± 0.025 g/cc@200 ft./hr ((60 m/hr) and 2.5 g/cc
esolution	18 in. (45 cm) (f	ull resolution)
le End		
e Point	5.1 ft. (1.5 m)	
Photoe	electric Factor Specification	ıs
ge	1-10 Barnes/el	ectron (B/e)
racy	± 0.25 B/e from 2-5 B/e	
epeatability	± 0.25 B/e@200	ft./hr (60 m/hr)
esolution	6 in. (150 mm) (f	full resolution)
End to Pe		_ ,
e Point	5.1 ft. (1.5 m)	
Acoustic	Standoff Caliper Specificat	ions
ge	0-2 in. (Out of housing)	
	±0.075 in. (0 to 0.5 in.)	
	±0.125 in. (0.5 to 1.0 in.)	
racy	±0. 25 in. (1.0 to 2.0 in.)	
	Out of housing	
ng Speed	180 ft./hr (@2	2 points/ft)
e Source	Cs137 Strength: 2 Curies (74 GBq)	
age	30 V	
Draw	350 mA~390 mA	
	Sliding Seperatability Sepolution Seperatability Seperatabil	20000 psi (13 13 14 15 15 15 15 15 15 15





(U Azimuthal Resistivity While Drilling (ARD) Geo-Vista



Applications

- For geosteering, the distance to the layer interface can be inferred to enhance the reliability and accuracy of geosteering.
- The azimuth resolution of 16 sectors close to the ground can be obtained. Its dynamic compensation can eliminate environmental interference.
- The 4 3/4" ARD and 6 3/4" ARD are compatible with HbuildLWD tools. This combination of drilling tools can accurately control the steering during drilling in complex formations.

Benefits

- Deeper detection radius, the approaching stratum can be warned in advance to make timely decisions.
- The 16-sector azimuth resolution can determine the azimuth angle close to the formation and avoid entering shale or other hard formations.
- Improve the rate of oil reservoir drilling.
- The oil-water interface can be clearly distinguished from the inclined top layer of shale
- Suitable for all types of mud.

Features

- ARD eliminates environmental influences to a great extent, such as wellbore size, tool eccentricity, tool bending degree and
- The multiple coil system makes the tool more sensitive to detection near the ground.
- The rectangular coil receiver enhances the detection depth of ring waves.

Introduction

ARD determines the azimuth angle close to the formation interface in real-time, such as the azimuth angle of the shale lens, cap layer or oil-water interface. The detection radius from the borehole axis is up to 17 feet (5.2 m). ARD is used for water-based mud, synthetic-based mud or oil-based mud.

Tool O.D.	4 3/4 in. (121 mm) / 6 3/4 in. (172 mm)
Applicable borehole size	5 7/8 in6 3/4 in. / 8 3/8 in10 5/8 in.
Common borehole size	6 1/8 in. (156 mm) / 8 1/2 in. (216 mm)
Tool length	11.03 ft. (3.36 m)
Tool weight	672 lbs (305 kg) / 1274 lbs (578 kg)
Equivalent stiffness ODxID	4.755 in.×2.165 in. / 6.755 in.×2.165 in.
Type of cut-off sub	NC38 / NC50 Female thread
upper connector	NC30 / NC30 Female tillead
Type of connector	GT4 / GT6
Operating specifications and r	estrictions
Displacement limited by LWD	125-350 gpm / 200-900 gpm
Maximum pull	534 klbs (2376kN) / 704 klbs (3132 kN)
Maximum bending torque	
Rotating	7 kft-lbs (10 kNm) / 20 kft-lbs (27 kNm)
Sliding	16 kft-lbs (22 kNm) / 61 kft-lbs (82 kNm)
Maximum temperature	300°F (150°C)
Maximum pressure	20000 psi (1378 bar)
Sensor Specifications	
Distance between measuring	E 46 th (1 66 m)
point and tool bottom	5.46 ft. (1.66 m)
Detection boundary	17 ft. (5.2 m)
Statistical repetition rate	±2%
Vertical resolution	24 in. (61 cm) (High resolution)
Azimuth quadrant	16

	Phase Difference	Range	0.1-3000 ohm-m
		Accuracy	± 1% (0.1-50 ohm-m)
			±0.5 mmho/m (> 50 ohm-m)
2 MHz	Attenuation	Range	0.1-500 ohm-m
		Accuracy	± 2% (0.1-25 ohm-m)
			±1.0 mmho/m (> 25 ohm-m)
		Vertical Resolution	8 in. (203 mm)
	Phase Difference	Range	0.1-1000 ohm-m
		Accuracy	± 1.0% (0.1-25 ohm-m)
			±1.0 mmho/m (>25 ohm-m)
400 kHz	Attenuation	Range	0.1-200 ohm-m
		Accuracy	± 5.0% (0.1-10 ohm-m)
			±5.0 mmho/m (>10 ohm-m)
		Vertical Resolution	12 in. (304 mm)





- Continuous,real-time,lithology-independent porosity without chemical sources.
- Resistivity-independent pay identification.
- Continuous,real-time permeability evaluation.
- Thin-bed characterization.
- Carbonate facies characterization.
- Irreducible water saturation.
- Gas-bearing reservoir evaluation.
- Heavy oil and tar identification.
- Hole size distribution

Introduction

By providing lithology-independent porosity, pore-size distribution, continuous permeability and direct hydrocarbon detection, the MRI delivers a step change in real-time producibility assessment for complex reservoirs.

While drilling a well with a challenging trajectory to target a complex carbonate reservoir the MRI (The high-quality, real-time magnetic resonance) to evaluate rock and fluid properties and obtain accurate lithology independent porosity and continuous permeability to optimize placement of the wellbore, the advanced petrophysical evaluation improved testing and completion design and calculated reservoir producibility for focus on well.

Max. Tool O.D.	6.9 in. (175 mm)	
(Single-sleeve Stabilizer)	(single-sleeve stabilizer)	
Max. Pressure	20,000 psi (137.9 MPa)	
Max. Temperature	;	300°F (150°C)
Make-up Length	32	2.38 ft. (9.87 m)
Weight	3385	.4 lbm. (1535.6 kg)
Borehole Size Range	8.25 to 10.	375 in. (20.96-26.36 cm)
Normal Collar O.D.	6-3/4 in. (1	71.5 mm) API tolerance
Thread Connections	GT6 bo	ox up/ GT6 box down
Vertical Resolution Static	1.5 in./min4 in./m	nin. (3.81 cm/min10.16 cm/min.)
Vertical Resolution Dynamic	10 in.@50 ft./h (2	25.4 cm@15 m/h)-0.25 m/min.
vertical Resolution Dynamic	20 in.@100 ft./h	(50.8 cm@30 m/h)-0.5 m/min.
Measurement of Porosity		0-100 pu
Min. mud Resistivity		0.02 ohm.m
Shell Diameter	1	5 in. (381 mm)
Shell Thickness	C	0.24 in. (6 mm)
Max. Number of Echoes		2000
Min. Echo, Spacing	0.6 ms	
T ₂ Distribution	С	0.5 to 5,000 ms
Precision	<10 pu/PAP	
Depth of Investigation	1	4 in. (356 mm)
Static Field Gradient		58 gauss
Freq of Sensitive Volume		245 kHz
Operating Position		Centralized
Hole Deviation	Vertical to Horizontal	
Power Supply	Turbine alternator	
Dogleg	Sliding	16°/100 ft. (16°/30 m)
Dogleg	Rotating	8°/100 ft. (8°/30 m)
Max. System Shock Level	30 min. at shock level 5 (50-gn threshold or	
wax. System Shock Level	accumulatd 20	00,000 shocks above 50 gn)
Torque	23,500 ft. lbf (31,800 N.m)	
Max. PH	<9	





- Optimize mud-weight selection
- Predict pore pressure independent of temperature and salinity effect.
- Identify top-of-cement
- Understand rock mechanical properties
- Measure porosity sourceless
- Position bit-on-seismic using synthetics
- Identify gas influx or formation gas.
- Perform many other standard sonic applications.

Introduction

Acoustic While Drilling (AWD) provides real-time compressional and shear wave travel-time measurements in slow and fast formations. Shear and comressional slowness with computed semblance values are acquired using a stateof-the art acoustic source combined with multiple arrays of receivers. Advanced downhole processing and wavefrom stacking techniques ensure reliable and fully compensated measurements.

Diameter		4.75 in.	6.75 in.
Tool O.D.		4.82 in. (122.43 mm)	6.9 in. (175.26 mm)
Hole Size		5.625 in. to 8 in.	8.5 in. to 10.625 in.
		(143 to 203 mm)	(216 mm to 270 mm)
Max. Operating	Temperature	300°F (150°C)	
Max. Operating	g Pressure	20,000 psi (137.9 MPa)	
Lengt	th	30 ft. (9 m)	23.8 ft. (7.254 m)
Weigl	ht	1,760 lbm (798 kg)	2,500 lbm (1,134 kg)
	HbuildLWD	GT4 box up/	GT6 box up/
Thread	HDUIIGEVVD	GT4 pin down	GT6 pin down
Connections	ComLWD	NC38 box up/	NC46 box up/
	Comevid	NC38 pin down	NC46 pin down
Makeup T	orque	8845 ftlbf (11,984 N.m)	25,000 ftlbf (33,895 N.m)
Max.	Rotating	15°/100 ft. (15°/30 m)	8°/100 ft. (8°/30 m)
Dogleg Severity	Sliding	30°/100 ft. (30°/30 m)	16°/100 ft. (16°/30 m)
Max. Flow	, Doto	400 gal US/min.	800 gal US/min.
IVIAX. FIOW	/ Kale	(1,514 L/min.)	(3,028 L/min.)
Max. Sand	Content	3%	
Max. LCN	1 Size	0.63 in. (16 mm)	
Average I	nertia	62 in.	
Transmitters	Number	1	
Receivers I	Number	4	
Measurement Type		Compression Wave & Shear Wave	
Accuracy, us/ft.		± 1	
(us/0.305 m)			
Measuremer	nt Range	All tools 40-230 us/ft. dependent on mud type	
Max. Shock		250 g for 100,000 cycles	
Measure Point From		14 ft. (4.267 m)	
Tool Bottom			





- Fracture characterization
- Borehole breakouts and geomechanics
- Borehole geometry evaluation
- Thin-bed identification
- Structural dip determination
- Lithology and porosity variations
- Secondary porosity identification
- Sedimentary features identification

Features

- Measures both Amplitude and Travel Time to obtain fully sampled images of the borehole surface.
- Enables client to evaluate borehole quality
- Enables a 256 sector circumferential resolution (1.4°) which is sufficient to fully sample the borehole wall in the typical ROP and RPM ranges experienced while drilling

Benefits

- High quality ultrasonic acoustic transducer
- 3D Borehole image visualization
- High sampling rate

Introduction

Ultrasonic Imaging While Drilling (UID) provides high-resolution borehole images while drilling in OBM/WBM.

Borehole imaging has been used to calculate borehole caliper, stress, breakout orientation, stratigraphic and geologic structure imaging in conventional wells. Borehole wall images are commonly used for fracture characterization during well planning to optimize hydraulic stimulation and maximize the possible return from a reservoir.

The image service is only avalable in memory mode while drilling, caliper is in real-time.

Maximum Temperature	300°F (150°C)
Maximum Pressure	20.000 psi (137.9 MPa)
Tool Size	6-3/4 in. (172 mm)
Hole Size	8-3/8 to 10 in. (213 mm to 254 mm)
Tool Weight	825 lbs. (375 kg)
Tool Length	8.8 ft. (2.68 m)
Logging Speed	Up to 400 ft./hr
Mud Type	OBM/WBM
Maximum Mud Weight	16 ppg
Azimuthal Sectors	256





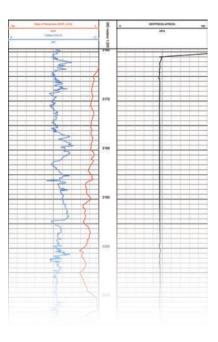
Pressure & Caliper Measurement While Drilling (PCD)



Ultrasonic Caliper Measurement While Drilling (CWD)

Features

- Accurate downhole measurement of equivalent circulating density.
- Swab/surge pressure monitoring while tripping and reaming.
- Accurate downhole measurement of hydrostatic pressure and effective mud weight.
- Accurate measurement of caliper



Introduction

PCD can accurately detect the annular pressure, the caliper, the borehole pressure and temperature. If PCD has no pressure measurement function, it is CWD (Ultrasonic Caliper Measurement While Drilling). It is used to judge the underground complex situation, such as well leakage, blowout, well inflow and monitoring well, and conductive to the control of well safety.

Tool Diameter	4.75 in. (120mm)/6.75 in. (171 mm)/	
1001 Diameter	8.25 in. (210 mm)	
Max. Pressure	20,000 psi (137.9 MPa)	
Max. Temperature	300°F (150°C)	
Make-up Length	6 ft2.8 in. (1.9 m)	
Operating Time Real-Time	No Limited	
Flow Range	100-300 gpm	
Data Acquisition Type	Real-time & Downhole Record	
Data Transmit Type	Positive pulse	
Pressure Measurement Range	0-25000 psi	
Caliper Measurement Range	0-2 in. (Out of housing)	
	±0.075 in. (0 to 0.5 in.)	
	±0.125 in. (0.5 to 1.0 in.)	
Caliper Accuracy	±0. 250 in. (1.0 to 2.0 in.)	
	Out of housing	





Features

- Safety, environmental protection, non-radioactive to operator
- High pulse neutron energy, high count rate, it can be extended for full spectrum measurement
- With open bus structure, it can be combined with other LWD tools

Introduction

The GCN is a logging-while-drilling tool that uses a pulsed neutron generator instead of a chemical source. The instrument only use one drill collar, it uses an open bus structure can be combined with other LWD tools. It is used to monitor formation porosity during drilling to achieve "chemical source free logging".

It consists of pulsed neutron generator, neutron detector, processing circuit It needs to be combined with PCD (Pressure & Caliper measurement while drilling) for neutron porosity corrected.

Tool Diameter	4.75 in. (120 mm)/6.75 in. (171 mm)/8.25 in. (210 mm)	
Max. Pressure	20,000 psi (137.9 MPa)	
Max. Temperature	300°F (150°C)	
Make-up Length	15 ft8.98 in. (4.8 m)	
Vibration	20 G, random frequency range 20~100,100 ~200 Hz	
Shock	500 G, 11 ms semi-sine wave	
Neutron Energy	2.5 MeV	
Neutron Yield	> 1*10 ⁸ n/s	
Measurement Range	0 to 100 p.u.	
Measurement Accuracy	0.5 p.u. below 10 p.u.; 5% of measurement otherwise	
Repeatability	± 0.6 p.u. @ 20 p.u. @ 200 ft./hr.	





- Optimization of mud weight
- Selection of optimal case
- Estimation of reserves
- Identification of fluids and their contacts.
- Reservoir model refinement
- Well placement

Benefits

- Mitigates risk through reservoir pressure management.
- Improves prediction of reserves using fluid typing.
- Enhances drilling performance through optimal mud weight.
- Saves time and cost by eliminating need for tool orientation

Features

- Provides formation pressure in drilling environment
- Provides direct pore pressure and mobility data for fluid typing and mud-weight optimization
- Used in any hole orientation—vertical or deviated
- Optimizes pretest volume and drawdown to formation characteristics
- Real-time measurements with quality control indicators



Introduction

Formation Tester While Drilling (FTD) service makes accurate measurements that provide direct pore pressure and mobility data for fluid typing, reservoir pressure management, and mud-weight control and optimization. It achieves time savings through a focus on operational efficiency and measurement versatility, accuracy, and quality.

		4.75 in.	6.75 in.
		Tool Design	
Meas	Measurement Type Probe pretest		etest
Pres	sure Gauges	High-precision quartz and strain	
Pov	ver Supplies	Battery, MWD turbine power	
		Measurement Specifications	3
Drob	Dimensions	1.75 in. (44.45 mm) OD	2.25 in. (57.15 mm) OD
Probe	e Dimensions	0.44 in. (11.18 mm) ID	0.56 in. (14.22 mm) ID
	Volume	0 to 25 cm ³ , fully	/ adjustable
Pretest	Drawdown Rate	0.1 to 2.0	cm³/s
	Delta Pressure	6,000 psi (41 MPa)	>6,000 psi (>41 MPa)
Set	ting Piston	1.38 in. (35.05 mm)	2.00 in. (50.00 mm)
Diar	neter Reach	more than tool OD	more than tool OD
		Up to 120 pretests	80 pretests of 5 min.
iviem	ory Capacity	depending on time downhole	duration
D "	0 "	150 pretests	
Batt	ery Capacity	1 cm³/s at 3,200 psi (22 MPa) dr	rawdown at 275 °F (125 °C
		General Specifications	
		4.82 in. (122.43 mm)	8.25 in. (209.6 mm)
Too	l Max. O.D.	5.75 in. (146.05 mm)	9.25 in. (234.95 mm)
		5.5 in. (139.7 mm) optional	with optional collar
To	ool Length	40.2 ft. (12.3 m)	31 ft. (9.45 m)
	Weight	2,000 lbm (907 kg) 2,866 lbm (1,300 kg	
GT4 box up/		GT4 box up/	GT6 box up/
Thread Connections		GT4 box down	GT6 box down
Operati	ng Temperature	300 °F (15	50 °C)
•		Mechanical Specifications	·
Max. Dogleg	Rotary Mode	15°/100 ft. (15°/30 m)	8°/100 ft. (8°/30 m)
Severity	Oli alia au Mar al a	30°/100 ft. (30°/30 m)	16°/100 ft. (16°/30 m)
Axia	Axial And Lateral 10g rms		ms
	Shocks	Tog II	
		Hydraulics	
Ма	x. External	20,000 psi (1	38 MPa)
I	Pressure	20,000 por (1	··· - /
FI	ow Range	0 to 400 galUS/min.	0 to 800 galUS/min.
Flow Range		(0 to 1,514 L/min.)	(3,028 L/min) (standard)
	Note:	Specifications are subject to ci	hange.



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